

Quickstart Guide xDB -5-200

Prerequisites:

- IFM control / display control
- CODESYS 3.5 with necessary packages
- DATA PANEL xtremeDB (DP-34044-5-200) module + accessories
- DC 12 / 24 V supply



Prepare CODESYS

Depending on the type of controller you are working with, the corresponding packages must be installed in CODESYS.

The packages for the respective controller are supplied or you can obtain them from the manufacturer's website or the CODESYS Store. A login may be required for the download.

• Open CODESYS

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- In the taskbar at the top via "Tools -> Package Manager... " open the package manager
- Right click on "Install..." and install the corresponding package
- In the following example the integration of an ifm display control is described

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Inst	tall EDS devic	e file				
	Open the de	vice repository v	ia "Tools->De	vice Reposito	ry" in the ta	skbar at the top.
	A new device	e can be installec	l via the "Inst a	all" button		
•	Double-click The device a	on the desired f ppears in the list	ile, alternative of added dev	ely select and vices	open the *.	e ds file manually.
i	The perma https://driv	link below alway ve.google.com/fi	rs leads to the le/d/13cXGUY	latest firmwa <u>YZOG3IUt_rC</u>	ire and *.ed	s file: <u>3VgUtkJ/view</u>
	😤 Geräte-Rep	ository				×
	Speicherort	~	Bearbeiten			
	Installierte Ge					
	Zeichenfolge	für eine Volltextsuche	Hersteller	<alle hersteller=""></alle>	~	Installieren
	Name	Herst ^ Data F	Deinstallieren Export.,			
		EtherCat Ethernet Adapter EtherNet/IP			~	
	⊡- 0 D:\3	4044-1-200\37000-561-0 Gerät "xDB0808-DIO CAN	10C.eds open" im Geräte-Repo	sitory installiert		
	🐞 Installiere (Gerätebeschreibung				×
	$\leftarrow \ \ \rightarrow \ \ ^{\prime}$	↑ 📙 « KINGSTON	> 34044-1-200	5 V	<i>,</i> ○ "34044-1-	200" durchsuchen
	Organisieren	✓ Neuer Ordner				E≡ - □ ②
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		Dateiname:		Ŷ	Alle unterstütz	ten Beschreibung 🗸
					Öffnen	Abbrechen



CODESYS project

- Open CODESYS
- Create a new project via File -> New project
- Select the corresponding control via the library and confirm with OK. The action may take some time.

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CAN communication

- Open the "Communication" node and right-click on "CAN -> Attach device".
- Select "ifm" under the manufacturer and append the "ifmCANbus
- Close window

The controller must be CANopen capable. If you want to work with SAE J1939, you can find a CODESYS function block for our modules under the following links: V2.3: <u>https://www.data-panel.eu/media/archive/CODESYS-23-Demo-DP-34044-x-000.zip</u> V3.5: <u>https://www.data-panel.eu/media/archive/CODESYS-35-Demo-DP-34044-x-000.zip</u>





CANopen Manager

- Right click on the just inserted "ifmCANbus -> Attach device".
- Change manufacturer filter to **<all manufacturers>.**
- Select the device via "CANopen -> CANopenManager -> CANopenManager" and attach it.

me CANopen_Manager				
Aktion				
🖲 Gerät anhängen 🔿 Gerät einfügen 🚫 Gerät ein	stecken 🔘 Gerä	it aktualisieren		
eichenfolge für eine Volltextsuche	Hersteller	<alle hersteller=""></alle>		
Name = feldbusse = fin CANopen = fin CANopen	Hersteller		Version	Beschreibung
	3S - Smart Sof	tware Solutions GmbH	3.5.16.0	CANopen Manager
CANopen_Manager_SIL2	3S - Smart Sof	tware Solutions GmbH	3.5.16.0	CANopen_Manager_SIL2
] Nach Kategorien gruppieren 🔲 Alle Versionen a	inzeigen (nur für B	Experten) 🗌 Veraltet	e Versionen a	inzeigen
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STEP 1

- Append a new device to the CANopen_Manager (right click -> Append device)
- Select the correct module based on the *.eds file and close it

STEP 2

- Open the configuration of the new device and set the node ID.
- Then go online, no errors should be displayed in CODESYS and the COM LED on the module should be permanently green.





ADDRESS

- The module has the base node ID 1 preset
- The offset set by means of wire jumpers on the module is added to the base node ID. If the node ID 2 is set in CODESYS, the offset 1 must therefore be jumpered on the module.

🚺 VENDOR ID

For the first series modules, the vendor ID was not stored in the firmware. In this case please either update the firmware of the module or deactivate the check of the vendor ID.



OUTPUT DO - GLOBAL

This module does not need to be configured, all outputs are designed as DO output

This module does not need to be configured

The CANopen I/O image can be used to declare and activate the variables for ports 1 to 4.

Either the entire integer variable **Output_1** can be used for this, alternatively the individual **bits** can also be declared.

Find		Filter Show all			- 🕂 Add FB for IO
Variable	Mapping	Channel Output_1	Address %QB0	Type USINT	Current Value
D5_DO_P1A	2.0	Bit0	%QX0.0	BOOL	TRUE
> D5_D0_P1B	***	Bit1	%QX0.1	BOOL	FALSE
***		Bit2	%QX0.2	BOOL	FALSE
^K ø		Bit3	%QX0.3	BOOL	FALSE
* @		Bit4	%QX0.4	BOOL	FALSE
· **		Bit5	%QX0.5	BOOL	FALSE
* @		Bit6	%QX0.6	BOOL	FALSE
		Bit7	%QX0.7	BOOL	FALSE
· · *		Output 2	%OB1	USINT	0

Go online with the controller and download the program. Force the variable **D1OutputB0** to "True". Alternatively, store a value in the **Dash1Output2** variable.



Port / Signal	Value	Port / Signal	Value
P1A	00 00 00 01	P3A	00 01 00 00
P1B	00 00 00 10	P3B	00 10 00 00
P2A	00 00 01 00	P4A	01 00 00 00
P2B	00 00 10 010	P4B	10 00 00 00



OUTPUT DO PORT 10A

With the outputs **1A** and **3A** actuators up to a current of 10A can be supplied. For this purpose, a value between 0-100 (0 - 10.0 A in 100 mA steps) can be stored in the index **2004:1**. If, for example, "**40**" is stored, the output current is set to max. 4.0 A.

Index:Subind	ex	Name			Zugriffstyp	Datentyp	Standardwert	^
16#1017:	16#00	Producer Heartbe	at Time		RW	UINT	16#7D0	
± 16#1400		Receive PDO Com	eceive PDO Communication Parameter 1					
± 16#1804		Transmit PDO Cor	Transmit PDO Communication Parameter 5					
± 16#1805		Transmit PDO Cor	Transmit PDO Communication Parameter 6					
± 16#1806		Transmit PDO Cor	nmunication Pa	arameter 7				
± 16#1807		Transmit PDO Cor	nmunication Pa	arameter 8				
± 16#1808		Transmit PDO Cor	nmunication Pa	arameter 9				
± 16#1809		Transmit PDO Cor	nmunication Pa	arameter 10				
± 16#2000		Module Global Co	nfiguration					
■ 16#2004		Module 10A Limit	Configuration					
:16#0	0	Highest sub-index	supported		RW	USINT	16#2	
:16#0	1	Port_1A			RW	USINT	0	
:16#0	2	Port_3A			RW	USINT	0	
16#5000		Response Messag	je					
± 16#5001		Status Message F1						
16#5002		Status Message F	2					U
<							>	
						7		
ame	Port_1	A						
ldex	16#20	04 😫	Bitlänge	8	÷			
ubindex	16#1		Wert	16#0		1		



DIAGNOSIS PORT 1A & B AMP FEEDBACK

For each individual signal pin (A or B), the current currently present can be read back.

To use the function, it is necessary to activate the diagnosis via SDO To do this, write "**10**" to index **5003:0** (default value), then the current present can be read back via the channel.

5	6	16#180B:16#01	Set and enable COB-ID	16#000003C1	32		0	
5	7	16#2000:16#03	Output_Mode	16#00	8		0	
5	8	16#2001:16#01	OUTMODE_1	16#10	8		0	
5	9	16#2001:16#03	OUTMODE_3	16#11	8		0	
6	0	16#2004:16#01	Port_1A	16#55	8		0	
6	1	16#5003:16#00	Highest sub-index supported	16#10	8		0	



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If no value is displayed, the index 1807 / 1808 :5 must be written with "CO" to switch on the cyclic exchange of the signals.

If a constant load is used, the applied current is governed by Ohm's law. When using PWMi, the control behavior of the output can additionally be influenced by the proportional and integral component (see p. 12).





DIAGNOSIS PORT 1A & B AMP FEEDBACK

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If now e.g. the channel Output_1 - Bit0 (Below declared as variable D5_DO_P1A) is switched on, the applied current on the channel Output_1 - Bit0 (Below declared as variable D5_DO_P1A _FB) can be read back.

If no value is displayed, the index 1807 / 1808 :5 must be written with "CO" to switch on the cyclic exchange of the signals.

📮 🍢		Output_1	%QB58	USINT	
🗇 D5_D0_P1A	×	Bit0	%QX58.0	BOOL	5410
···· **		Bit1	%QX58.1	BOOL	
*		Bit2	%QX58.2	BOOL	
**		Bit3	%QX58.3	BOOL	
* @		Bit4	%QX58.4	BOOL	
🍫		Bit5	%QX58.5	BOOL	
* @		Bit6	%QX58.6	BOOL	
* @		Bit7	%QX58.7	BOOL	
÷		Output_2	%QB59	USINT	
🗄 ᡟ		d1-d8	%IB200	USINT	
÷		d9-d16	%IB201	USINT	
🗄 ᡟ		Active_Fault_Code	%IB202	USINT	
÷		Configuration_ID	%IB203	USINT	
🗄 🍫		d1-d8_Message	%IB204	USINT	
🗐 🏘		d9-d16_Message	%IB205	USINT	
🗄 🍫		Status_Output1-2	%IB206	USINT	
🗐 🍫		Status_Output3-4	%IB207	USINT	
🗄 🍫		Status_Output5-6	%IB208	USINT	
÷		Status_Output7-8	%IB209	USINT	
🗄 🍫		Power	%IB210	USINT	
÷		Save_Counter	%IB211	USINT	
🗄 🍫		VBAT	%IW106	UINT	
÷		TEMP	%IW107	UINT	
💼 🍫		CNFG1	%IW108	UINT	
i		CNFG2	%IW109	UINT	
D5_DO_P1A_FB	*	Port_1A	%IB220	USINT	5390
÷. *>		Port 1B	%IB221	USINT	



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DIAGNOSIS PORT 1 PIN A & B STATUS / FEHLER

The status of the individual outputs can be queried by activating index **5001**. Subsequently, the status of the outputs on **port 1 and 2** can be queried via the variable **Status_Output 1-2**. If an output is activated, the first bit (**DP_DO_P1A_OK**) is set. If an error occurs at the output, the second bit (**D5_DO_P1A_FLT**) is set.

If no value is displayed, the index 1805:5 must be written with "C0". This SDO takes care of the cyclic exchange of the data.

34	16#1809:16#01	Set and enable COB-ID	16#000002EA	32	
35	16#5001:16#00	Highest sub-index suppo	16#8	8	
36	16#1805:16#05	Event Timer	16#C0	16	

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⊒™ ø		Output_1	%QB58	USINT	
🍫 D5_D0_P1A	*	BitO	%QX58.0	BOOL	TRUE
^K ø		Bit1	%QX58.1	BOOL	FALSE
···· * ø		Bit2	%QX58.2	BOOL	FALSE
🍫		Bit3	%QX58.3	BOOL	FALSE
🍫		Bit4	%QX58.4	BOOL	FALSE
🍫		Bit5	%QX58.5	BOOL	FALSE
🍫		Bit6	%QX58.6	BOOL	FALSE
L 🍫		Bit7	%QX58.7	BOOL	FALSE
- * ø		Output_2	%QB59	USINT	
B 🍫		d1-d8	%IB200	USINT	
an 🍫		d9-d16	%IB201	USINT	
B 🍫		Active_Fault_Code	%IB202	USINT	
i - 🍫		Configuration_ID	%IB203	USINT	
B 🍫		d1-d8_Message	%IB204	USINT	
an 🍫		d9-d16_Message	%IB205	USINT	
a 🧤		Status_Output1-2	%IB206	USINT	
- 🏷 D5_D0_P1A_OK		Bit0	%IX206.0	BOOL	TRUE
D5_DO_P1A_FLT		Bit1	%IX206.1	BOOL	FALSE
🍫		Bit2	%IX206.2	BOOL	FALSE
🍫		Bit3	%IX206.3	BOOL	FALSE
🍫		Bit4	%IX206.4	BOOL	FALSE
🍫		Bit5	%IX206.5	BOOL	FALSE
🍫		Bit6	%IX206.6	BOOL	FALSE
		Bit7	%IX206.7	BOOL	FALSE



DIAGNOSIS TEMP & VOLTAGE

Further diagnostic data like e.g. the temperature of the module or the bus voltage may be read out. For this the index **5002** should be activated.

Afterwards the voltage or the module temperature can be read back in the variable **VBAT or TEMP.**

The voltage is displayed decimally with a resolution of 0.1 V.

The temperature has the resolution -100 °F to 300 °F which is displayed in 0-4000 bit (factor 10). For the display of the temperature in °C, this value must still be converted from Fahrenheit to Celsius. e.g. ((1815 / 10) - 100) = 81.5 °F - 32 × 5/9 = 27.5 °C



If no value is displayed, the index 1806:5 must be written with "CO". This SDO takes care of the cyclic exchange of the data

37	16#5002:16#00	Highest sub-index supported	16#5	8	
38	16#1806:16#05	Event Timer	16#C0	16	

· ₩- *		Power	%IB80	USINT	20
18- 3 0		Save_Counter	%IB81	USINT	0
🖶 🦘 DSVBAT	***	VBAT	%IW41	UINT	241
🖲 🦘 D5Temp	×	TEMP	%IW42	UINT	1815
⊕- * ₽		CNFG1	%IW43	UINT	3
·⊞*•		CNFG2	%IW44	UINT	6
18 - X		Port_1A	%IW45	UINT	0
·⊞*•		Port_1B	%IW46	UINT	0
😟 - 🍫		Port_2A	%IW47	UINT	0
· ⊞ ¥ø		Port_2B	%IW48	UINT	0
+ - *		Port_3A	%IW49	UINT	0
· ● - *		Port_38	%IW50	UINT	0
⊞-¥ø		Port_4A	%IW51	UINT	0
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DIAGNOSIS AUSGANGSSPANNUNG P1

In addition, the status of the output voltage supply can be queried. Index **5001** must be activated for this purpose. Subsequently, the status of the supply circuit **P1** can be queried in the variable Power.

Bit 1 / 2 = P 1



If no value is displayed, the index 1805:5 must be written with "C0". This SDO takes care of the cyclic exchange of the signals.



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34	16#1809:16#01	Set and enable COB-ID	16#000002EA	32	
35	16#5001:16#00	Highest sub-index suppo	16#8	8	
36	16#1805:16#05	Event Timer	16#C0	16	

> D3Power	×.	Power	%IB80	USINT	20
-*		Bit0	%DX80.0	BOOL	TRUE D1
- **		Bit1	%IX80.1	BOOL	FALSE
-*		Bit2	%IX80.2	BOOL	FALSE
- *		Bit3	%DX80.3	BOOL	FALSE
-*		Bit4	%IX80.4	BOOL	FALSE
- **		Bit5	%IX80.5	BOOL	FALSE
- **		Bit6	%DX80.6	BOOL	FALSE
*		DIL/	781.00.7	DOOL	1 Placeto
*		Save_Counter	%IB81	USINT	0
D3VBAT	×.	VBAT	%IW41	UINT	241
D3Temp	×	TEMP	%IW42	UINT	1815
**		CNFG1	%IW43	UINT	3







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